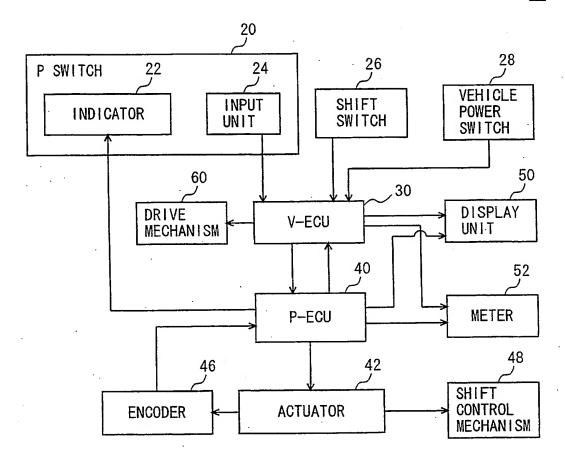
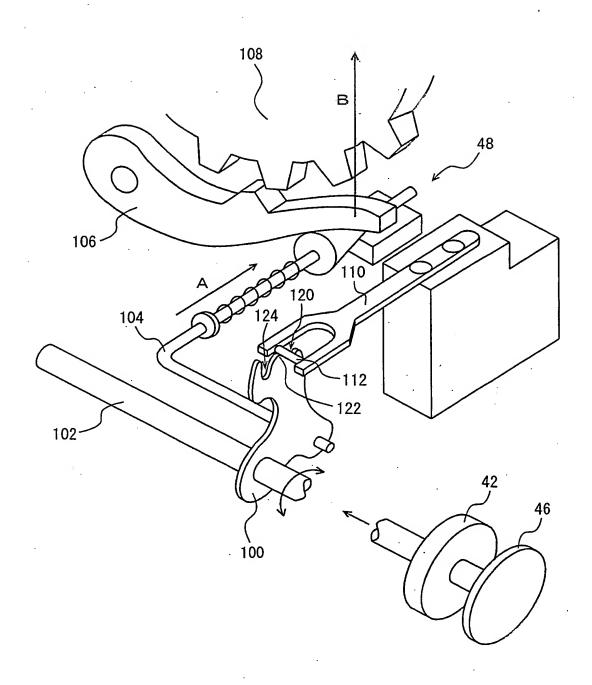
FIG. 1

10



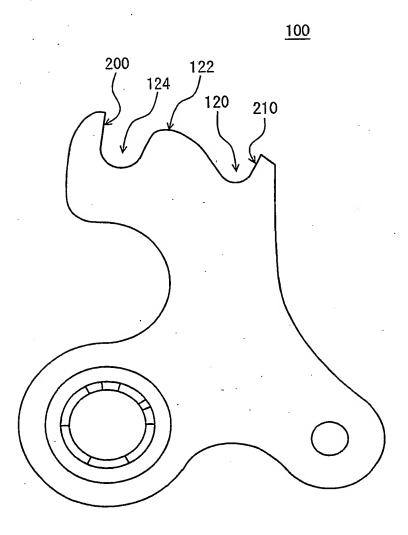
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F.I.G. 2



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FIG. 3



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## FIG. 4

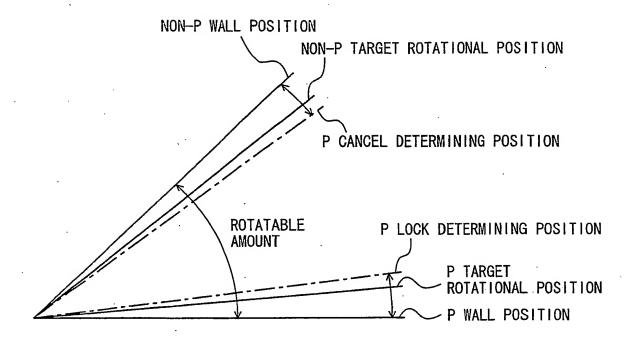


FIG. 5A

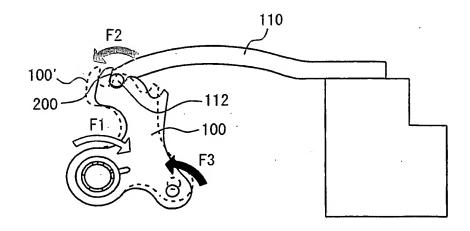
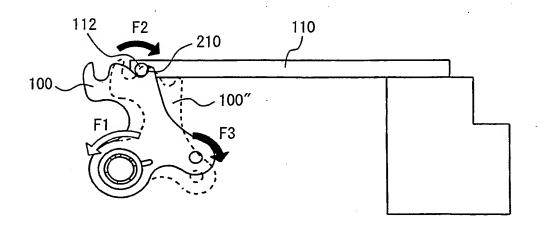


FIG. 5B



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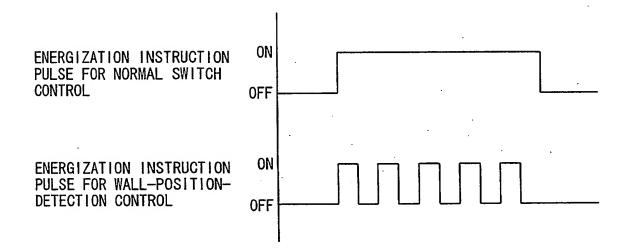
## F I G. 6

PRECEDING TRIP			WALL POSITION	
SHIFT RANGE	ACTUAL ROTATABLE AMOUNT	ECU INSTRUCTION	P WALL POSITION	NON-P WALL POSITION
P RANGE	DETECTED		DETECT	NOT DETECT
PRANCE	UNKNOWN		DETECT	DETECT
NON-P RANGE	DETECTED		NOT DETECT	DETECT
NON-1 IVANUE	UNKNOWN		DETECT	DETECT
UNKNOWN		P RANGE	DETECT	DETECT
		NON-P RANGE	DETECT	DETECT

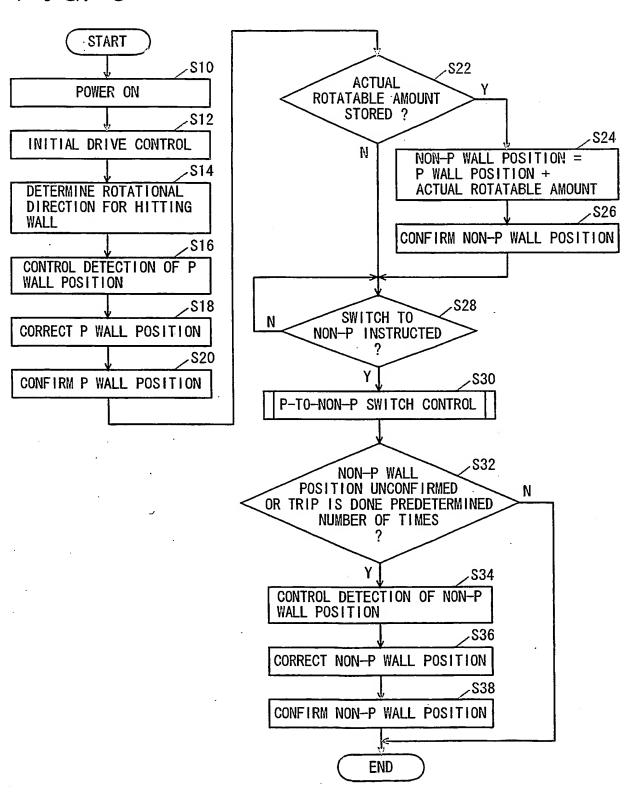
DETECTION OF WALL POSITION	V OF WALL	ACTUAL POTATABIE	METHOD OF CALCULATING TARGET ROTATIONAL POSITION	RET ROTATIONAL POSITION
P WALL POSITION	NON-P WALL POSITION	AMOUNT	P TARGET ROTATIONAL POSITION	NON-P TARGET ROTATIONAL POSITION
DETECTED	DETECTED	DETECTED	P WALL POSITION + MARGIN	NON-P WALL POSITION - MARGIN
ATT OT THE	MINOINAIM	DETECTED	P WALL POSITION + MARGIN	P WALL POSITION + ACTUAL ROTATABLE AMOUNT - MARGIN
VEIEVIEU	OINDIAN	UNKNOWN	P WALL POSITION + MARGIN	P WALL POSITION + DESIGNED ROTATABLE AMOUNT
HRIVAIOURA	DETENTED	DETECTED	NON-P WALL POSITION - ACTUAL ROTATABLE AMOUNT + MARGIN	NON-P WALL POSITION - MARGIN
UNINUIN	VEIEVIEV	UNKNOWN	NON-P WALL POSITION - DESIGNED ROTATABLE AMOUNT	NON-P WALL POSITION - MARGIN

Е ] Э

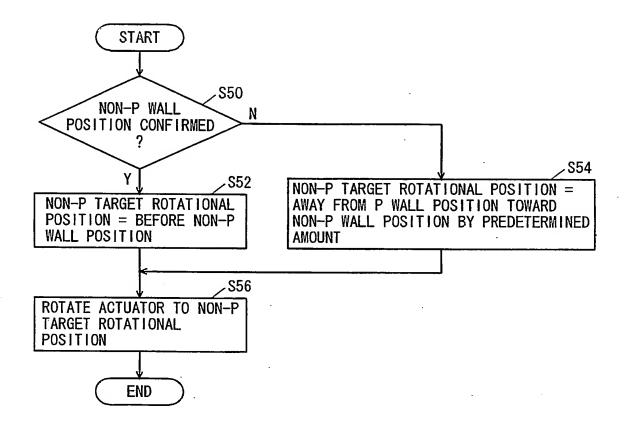
F I G. 8



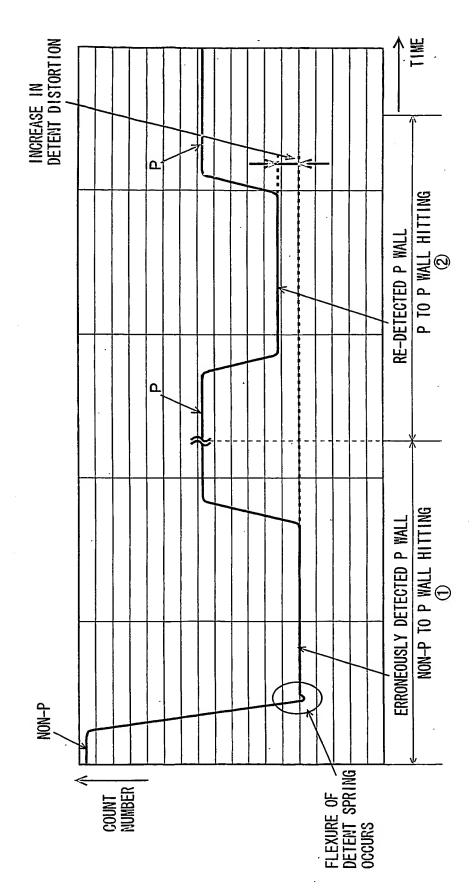
F I G. 9



## FIG. 10



HITTING OF ROLLER INITIALLY IN NON-P AGAINST P WALL



F I G. 12A

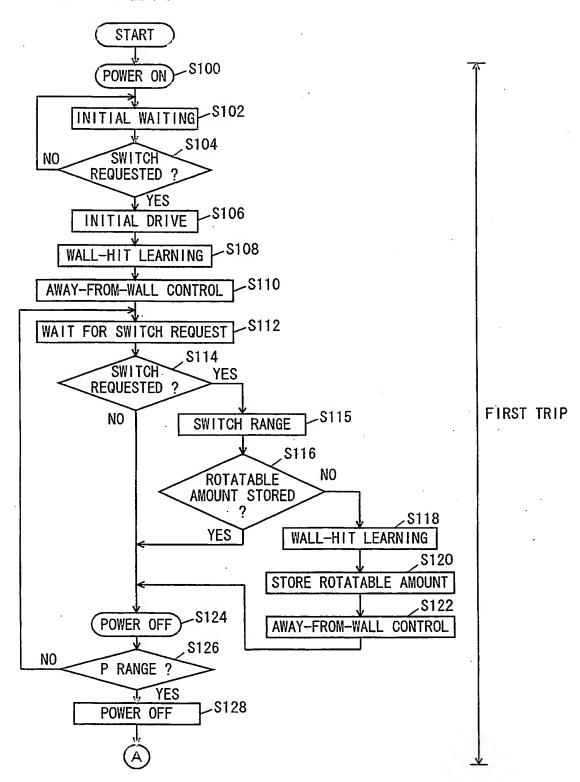


FIG. 128

